Simulation will be divided into 2 tasks, Marios and mete will going to work on simulation. We need the pusher part of the simulation ready by Monday.

Research on the optical sensors (Celine)

Start developing Arduino (Can & Serkan)

Updating the mesh file for the simulation (Ismail)

Final version of the rubric

Robotic arm cannot be at the top of the conveyor belt!

Material list and what to order

Improvements

Let us know when you are going to miss the meeting